

Introduction

- **Dynamic Mode Decomposition (DMD)** is a simple, interpretable data-driven technique to disentangle space-time dynamics
- Provides a linear approximation to a dynamical system
- Input: snapshots arranged in two **data matrices**
 $X = [X_1 \ X_2 \ \dots \ X_n], Y = [Y_1 \ Y_2 \ \dots \ Y_n], Y_i = X_{i+1}$
- **DMD matrix** $A = YX^\dagger$ solves:

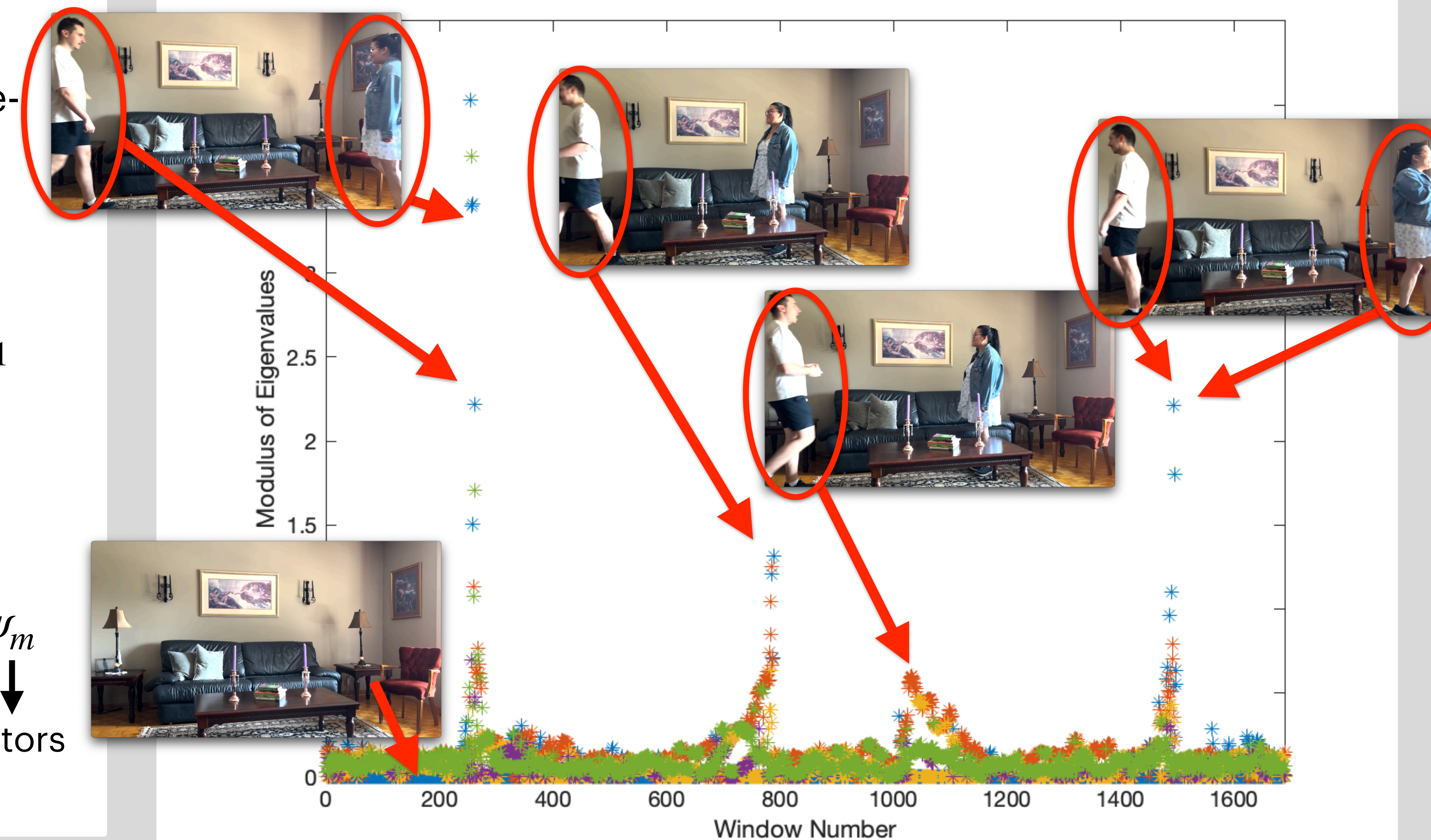
$$\operatorname{argmin}_{A \in \mathbb{C}^{M \times M}} \|Y - AX\|_F^2$$

If A is diagonalizable, we can decompose: $X_k = \sum_{m=1}^M c_m \lambda_m^k \psi_m$

Objective: leverage this to implement an automatic motion detection system for video

Eigenvalues
Eigenvectors

Motion Detection Scheme



Eigenvalue average in each window

$$\mu^{(k)} = \frac{1}{r} \sum_{i=1}^r |\omega_i^{(k)}|$$

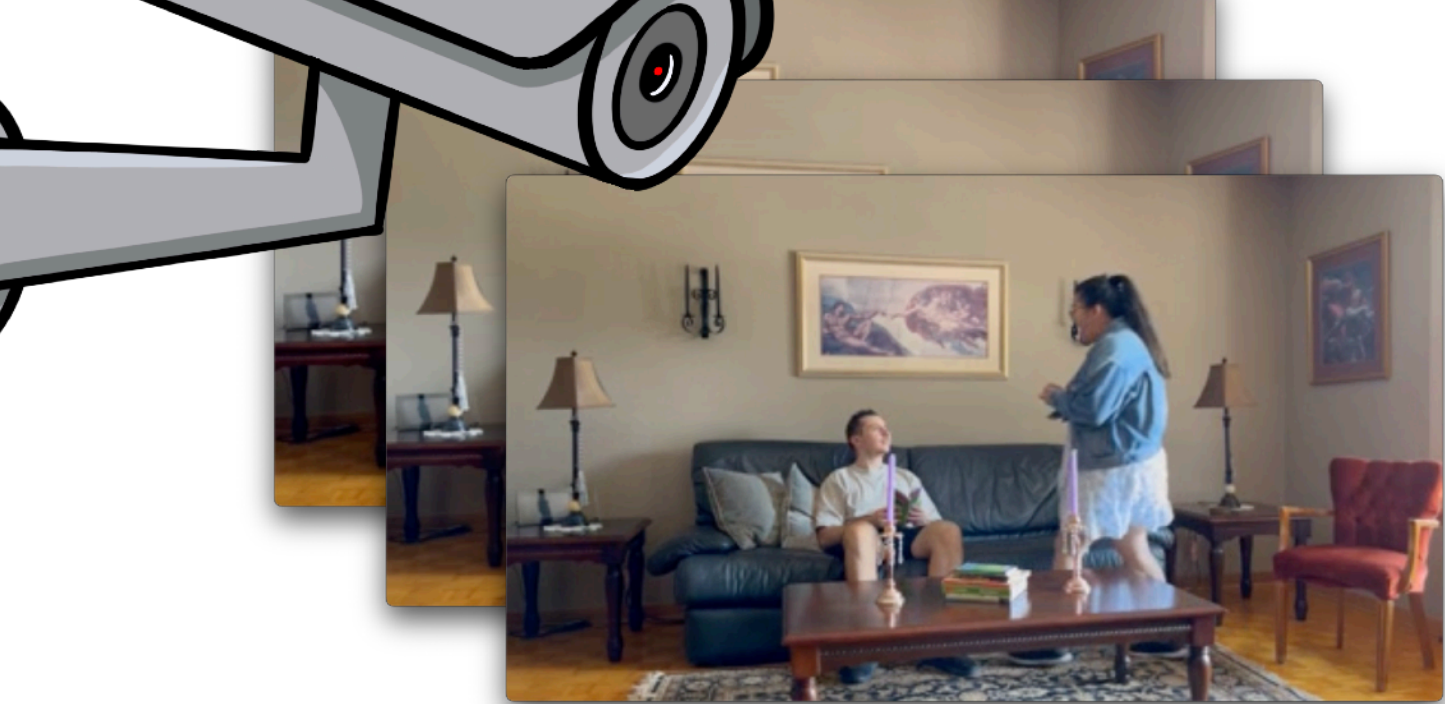
Compute relative change

$$\Delta = \frac{|\mu^{(k+1)} - \mu^{(k)}|}{|\mu^{(k)}|} \Delta > \Delta^*$$

Motion Detected!

Optimizing Δ^* requires an error measure: $E = FP + c \cdot FN$

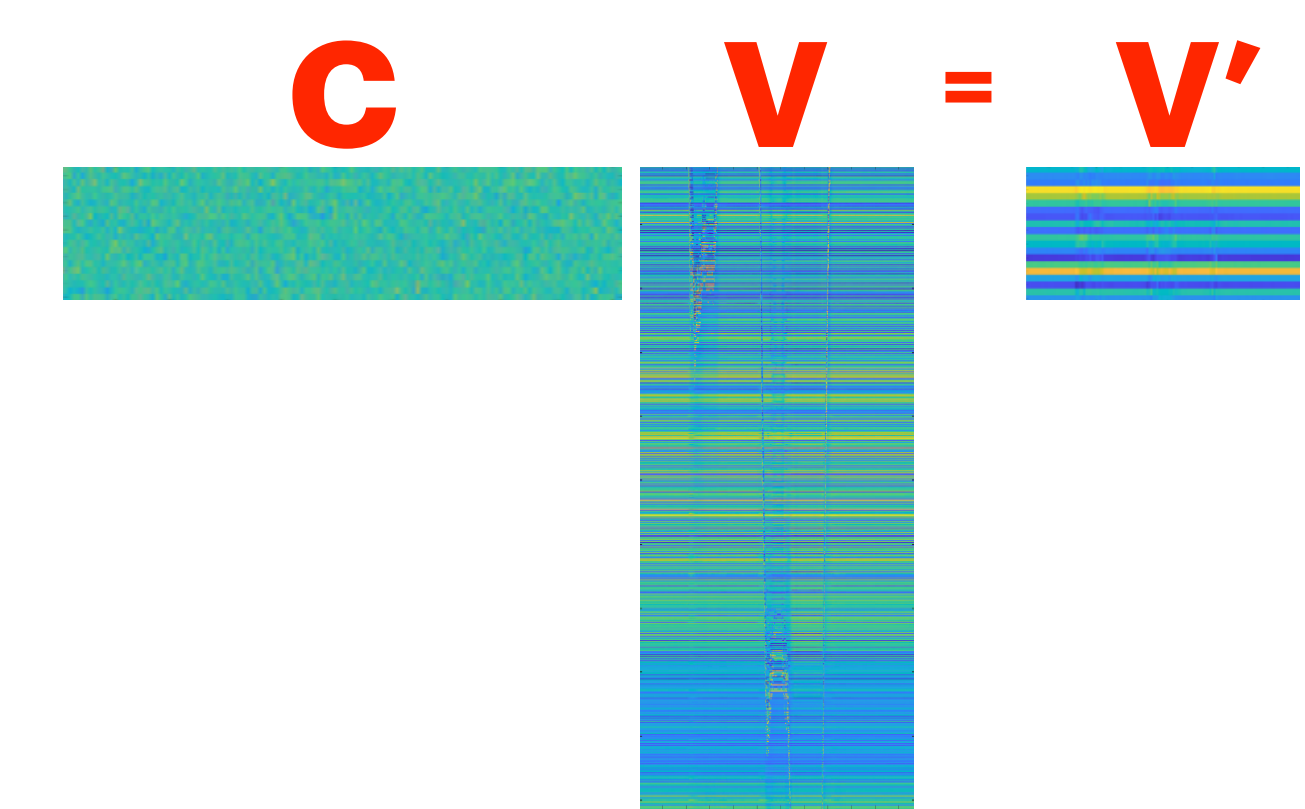
DMD Algorithm



Input: video matrix $V \in \mathbb{R}^{M \times N}$

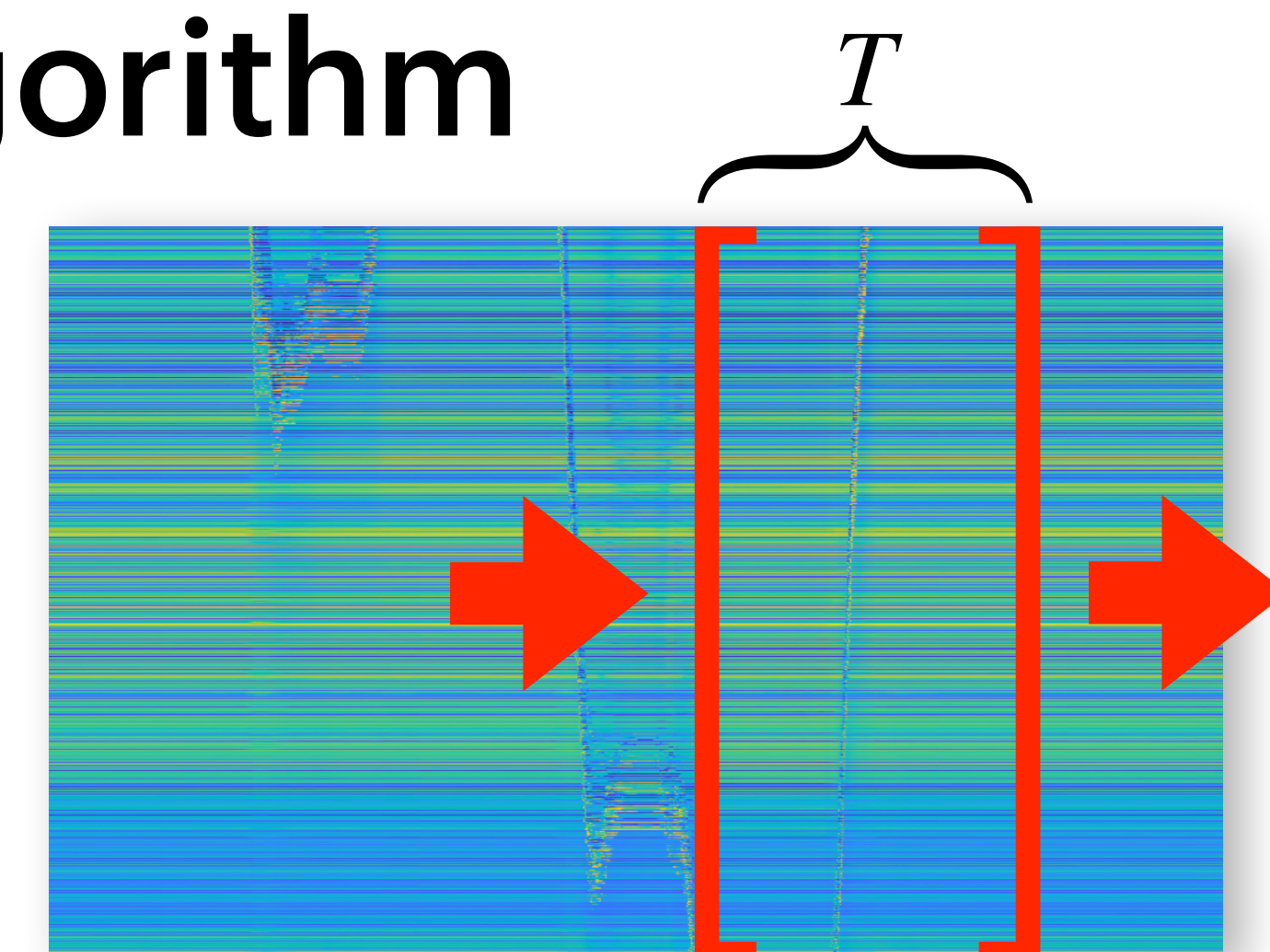
1. Compressed DMD

High dimensional video data V is compressed using a random matrix C : $V' = CV$



2. Sliding Window DMD

Streaming data is separated into windows of size T to apply DMD



3. Rank 'r' Approximation

Take the SVD of compressed data matrix X' to find best rank r approximation: $X' \approx U_r \Sigma_r V_r^*$

4. Rank Reduced DMD Matrix

Calculate the projection of the DMD matrix A onto U_r :

$$\tilde{A} = U_r^* A U_r = U_r^T Y_2 V_r \Sigma_r^{-1}$$

5. Extract Eigenvalues

$$\tilde{A}v = \lambda v \implies \omega = \log \lambda / \Delta t$$

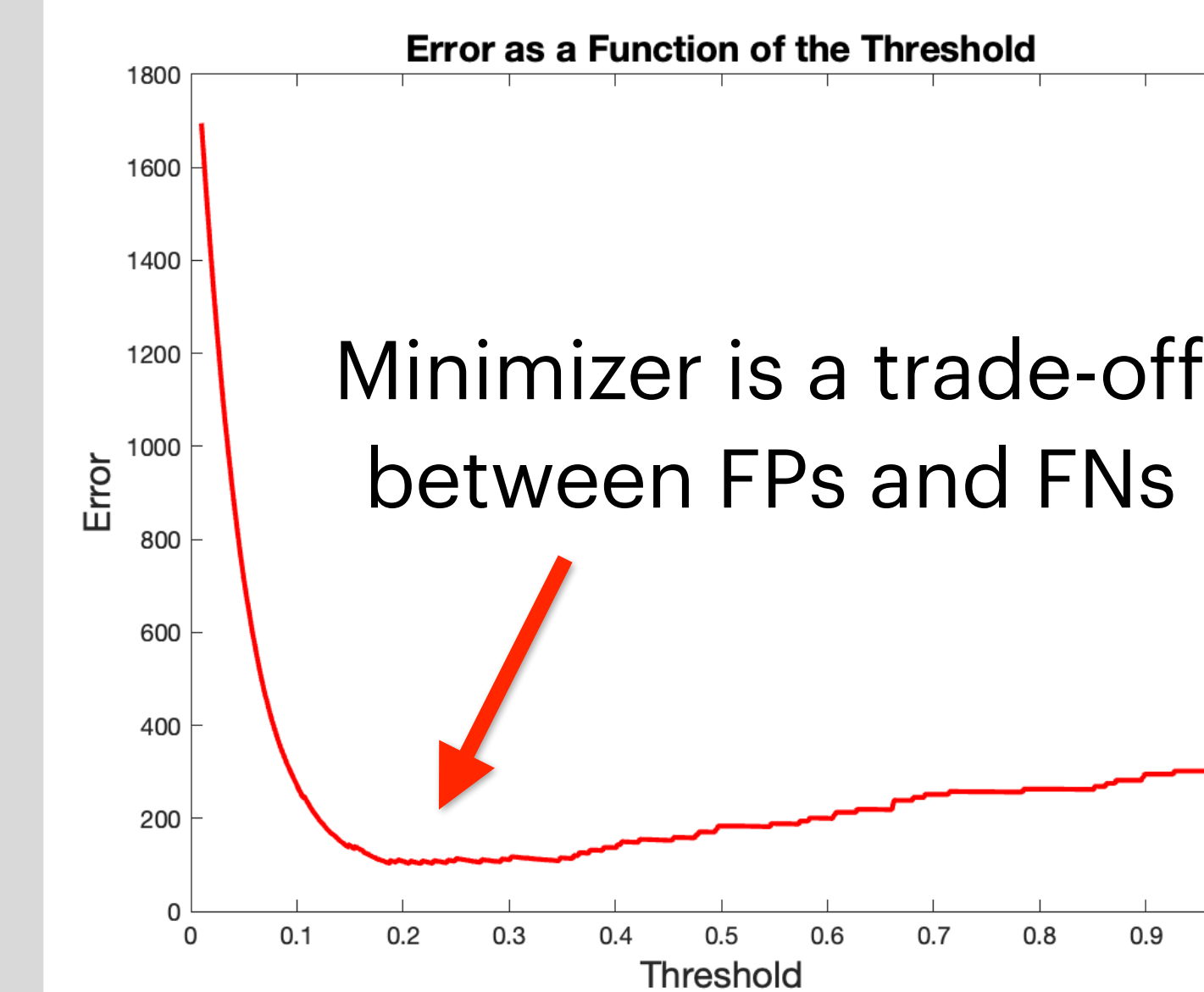
Output: matrix of eigenvalues

Event Detection Training

Pseudo k-fold Cross Validation

1. Shuffle the given dataset randomly
2. Split into k groups (**folds**) of equal size
3. For k iterations
 1. Separate into **training set (T)** and **validation set (V)**
 2. Train the model on T, tracking error for each Δ^*
 3. Threshold with smallest average error is optimal
 4. Test the threshold value on V and compute error
 5. Threshold with lowest overall error is optimal

1	V	T	T	T
2	T	V	T	T
3	T	T	V	T
4	T	T	T	V



Results

	Iter 1	Iter 2	Iter 3	Iter 4
Threshold	0.450	0.348	0.410	0.348
Avg. err.	17.00	31.33	33.67	68.33
Threshold	0.348	0.348	0.360	0.450
Avg. err.	91.00	29.00	28.80	127.00

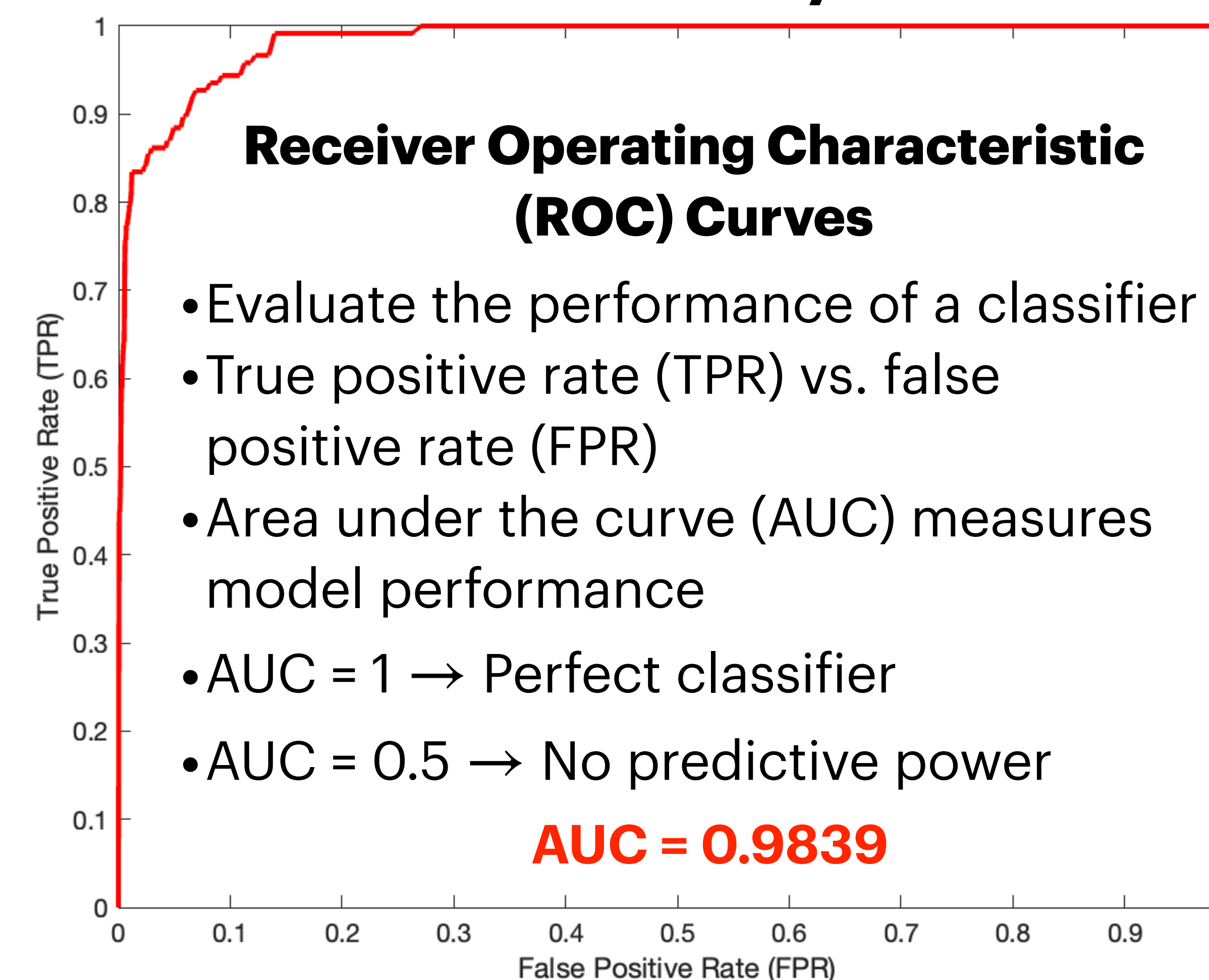
Hard Easy

Conclusion

We have proposed a simple, effective, and interpretable method to detect movement in video

- Method works best when subjects are clear and isolated
- Future work: comparison with standard motion detection methods and training with a larger video database

Does it Actually Work?



References

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2. Erichson, N.B., Brunton, S.L. & Kutz, J.N. Compressed dynamic mode decomposition for background modeling. J Real-Time Image Proc 16, 1479-1492 (2019).
3. Gareth James et al. An Introduction to Statistical Learning with Application in R. 2nd ed. Springer Texts in Statistics. Springer New York, NY, July 2021, pp. XV-607.
4. J. Nathan Kutz et al. Dynamic Mode Decomposition. Society for Industrial and Applied Mathematics, 2016.

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